

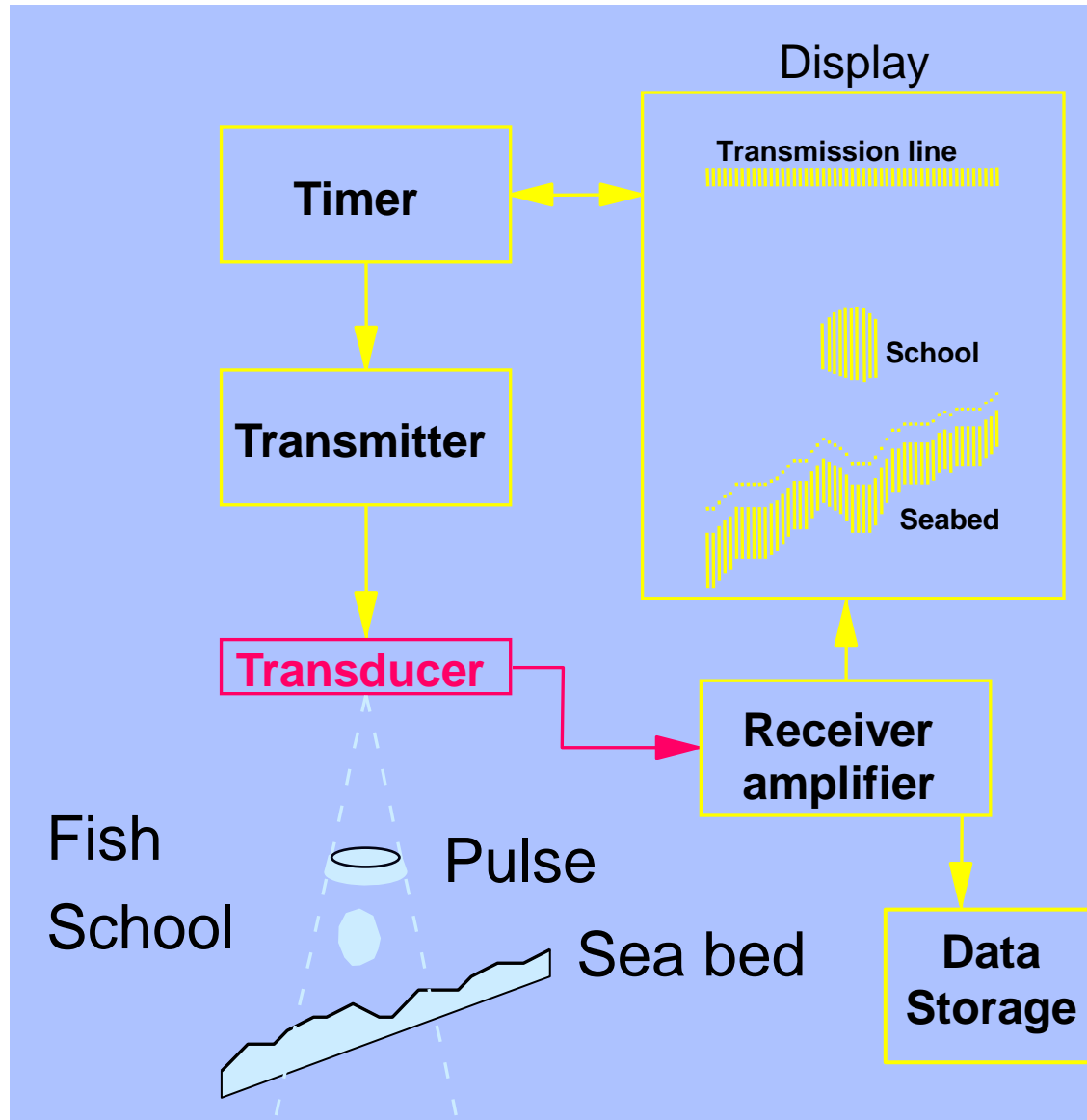
# Sonar Hardware



# Why Not Use Light?

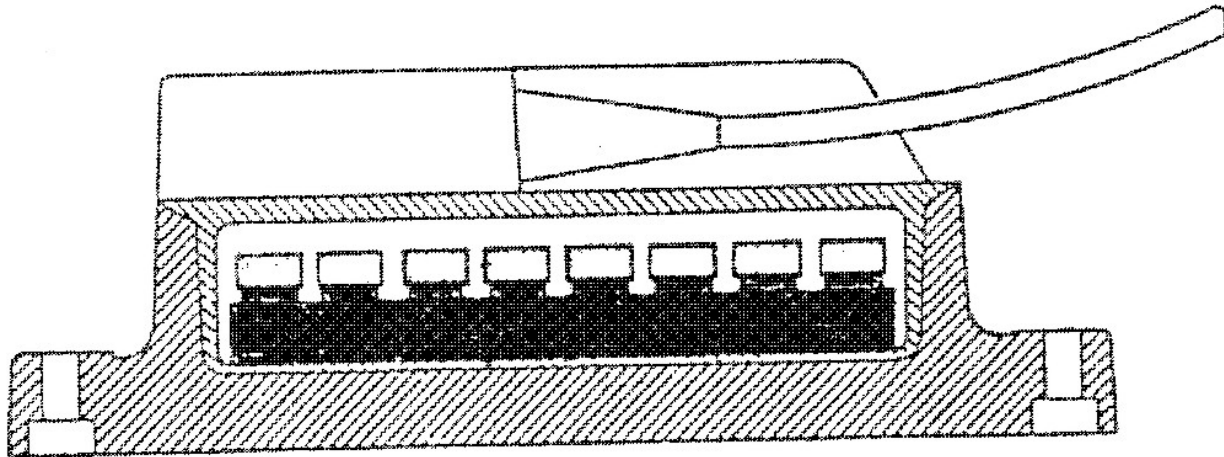


# Sonar Components



# Transducers

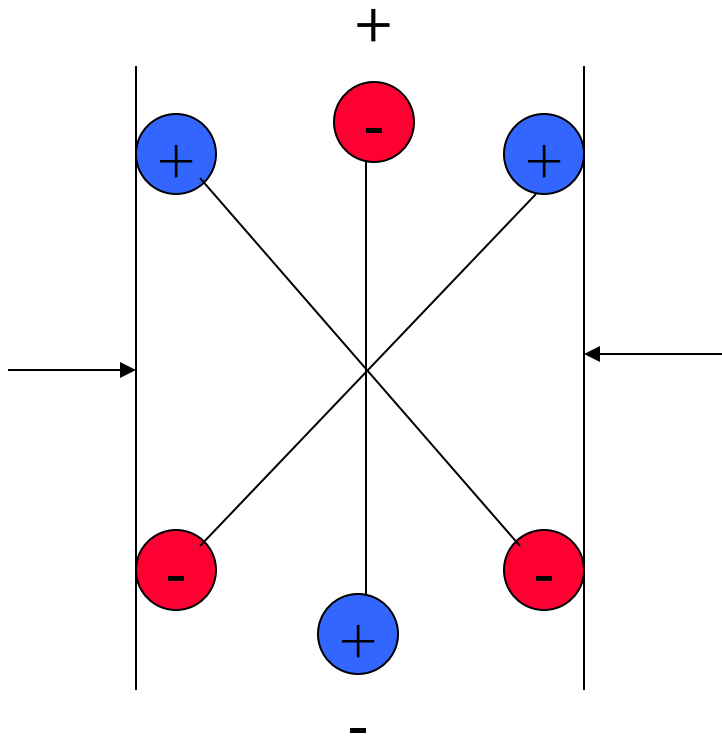
- piezo-electric: piezein (Greek) to squeeze or press
- apply voltage <--> generate pressure
- sandwiched material: steel, quartz crystal, steel
- efficiency: ceramic 50%, nickel 25%



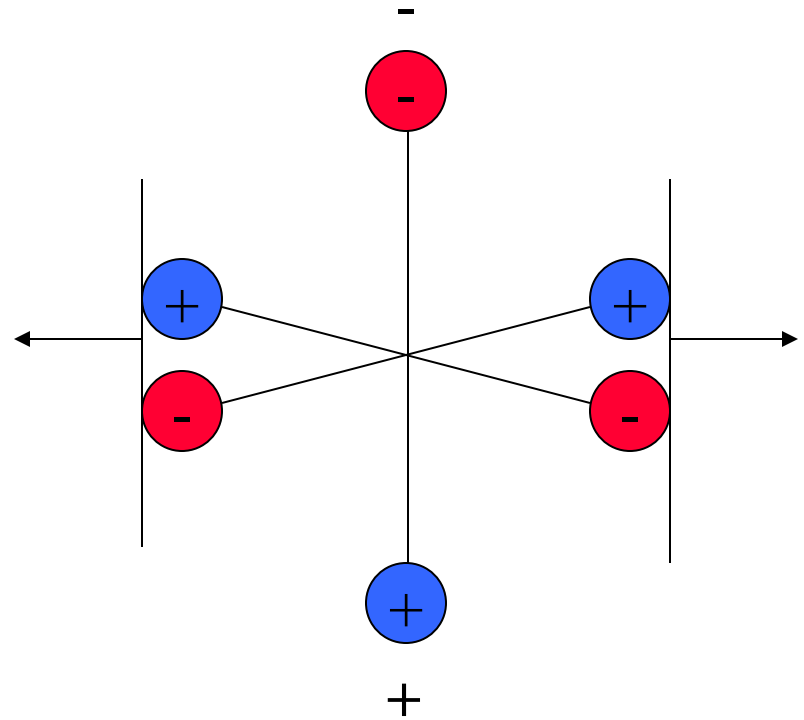
# Piezo-electric Effect

- crystals of silicon dioxide

Compression

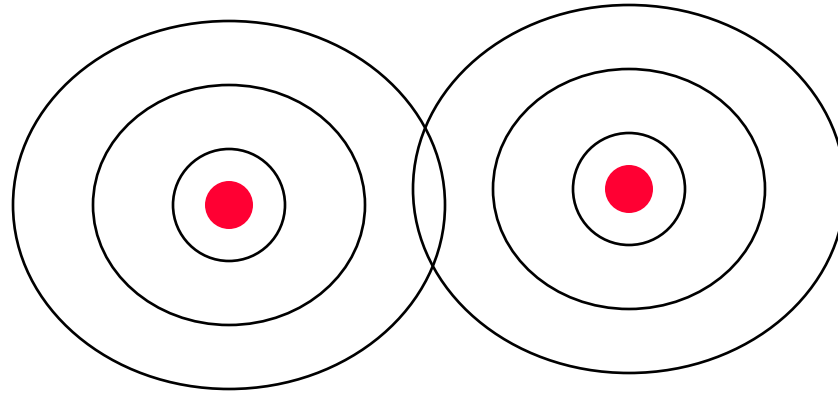


Tension/Rarefaction



# Hugen's Principle: Point Source Scattering

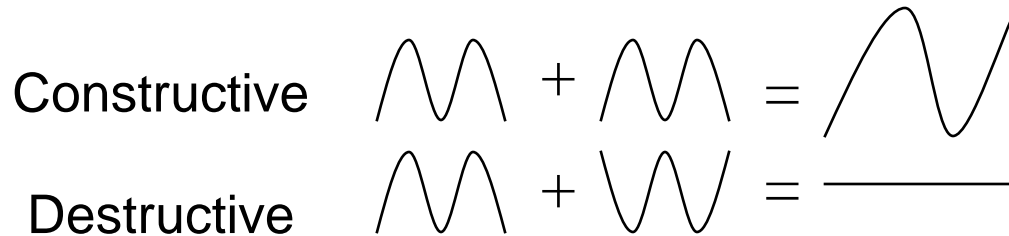
Every point in a wave field acts as a point source



Interference among sources (e.g. ripples in a pond)

Constructive  $\text{M} + \text{M} = \text{M}$

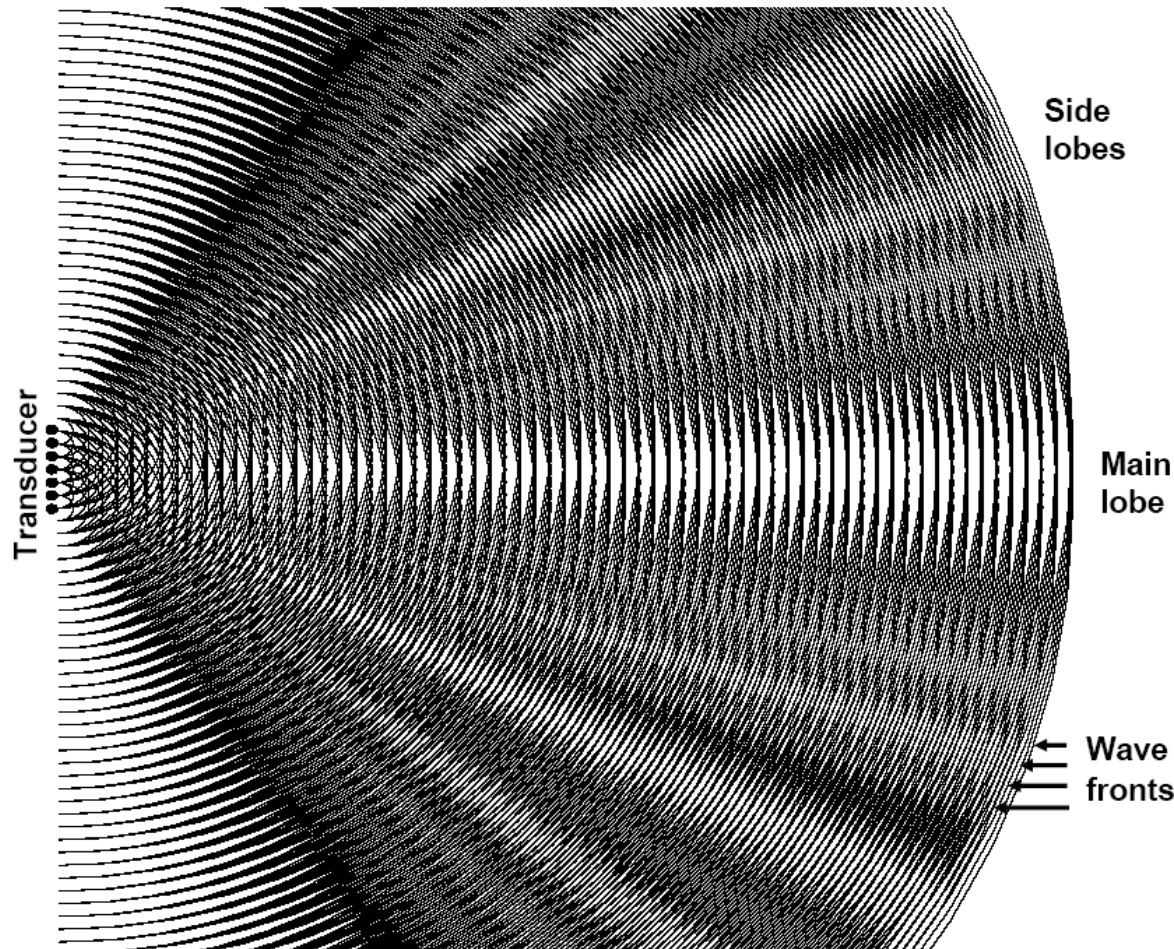
Destructive  $\text{M} + \text{M} = \text{—}$

A diagram illustrating wave interference. It shows two rows of wave patterns. The top row, labeled 'Constructive', shows two identical sine waves (represented by 'M' shapes) being added together to form a single wave with double the amplitude. The bottom row, labeled 'Destructive', shows a sine wave (represented by 'M' shape) being added to an inverted sine wave (represented by 'W' shape) to form a flat line, indicating zero net displacement.

# Hyugen's Principle in Action



# Transducer Beam Pattern



Shading used to form main lobe through constructive and destructive interference

(pebbles thrown in a pond)

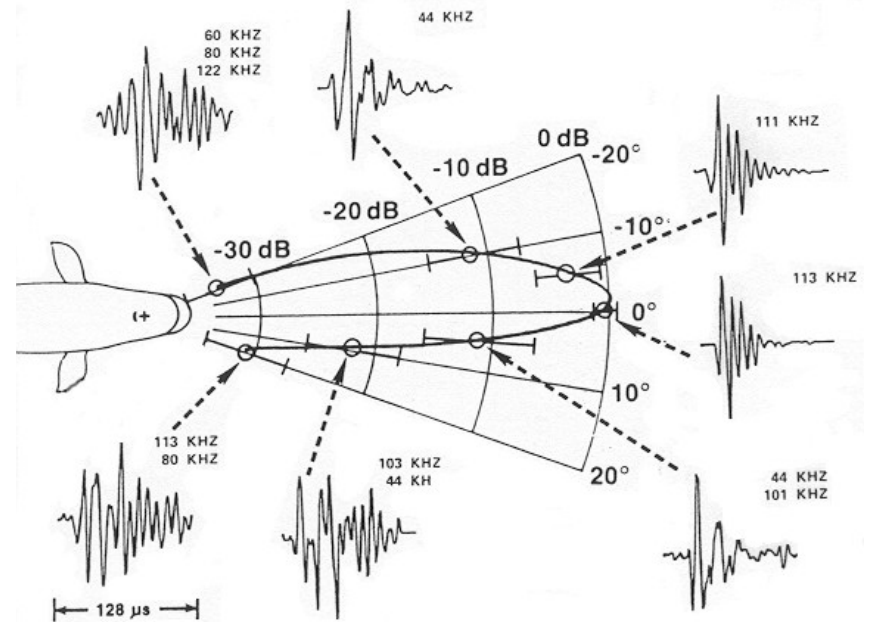
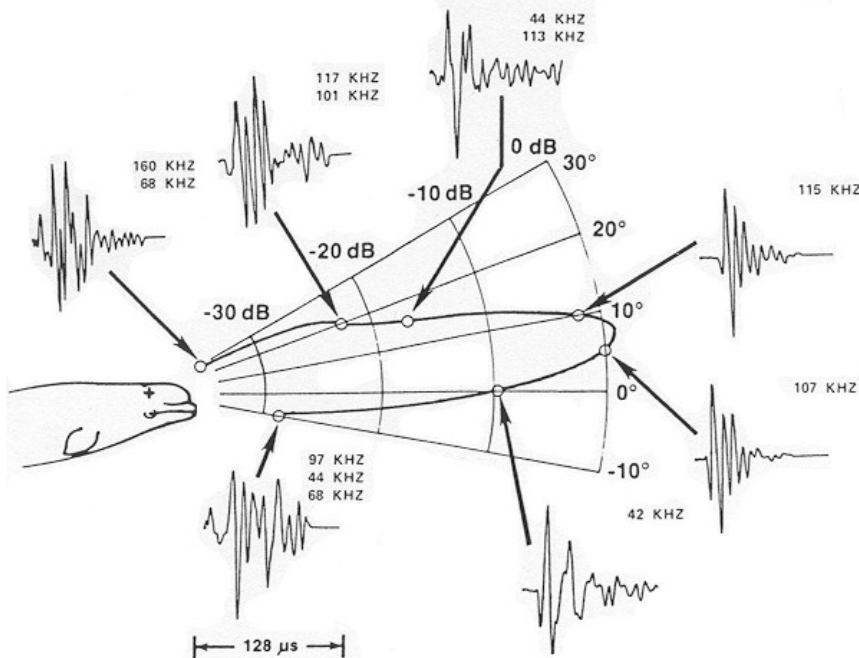
\* sound pattern is independent of intensity

(flashlight with low batteries)



# Marine Mammal Beam Patterns

## Beluga (*Delphinapterus leucas*)



Au et al. 1987

# Forming an Acoustic Beam

- focusing energy in main lobe

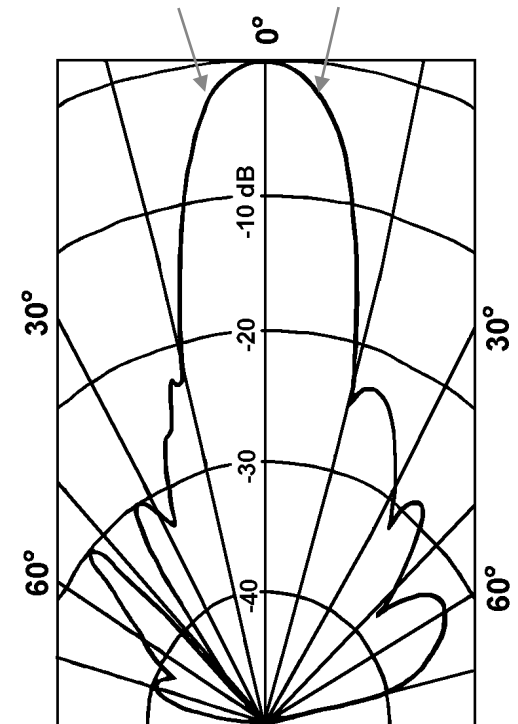


tail mass

head mass

small source: directional (e.g. tweeter)

large source: omnidirectional (e.g. subwoofer)



2 D Plot

Beam angle = half power:  $10 \cdot \log_{10}(0.5) = -3 \text{ dB}$

# Focusing Sound in Cetaceans

- many cetaceans have 'lens-like' structures to focus sound

Application of ray tracing and Snell's law (for sound): wave front is retarded in slower (i.e. less dense) medium

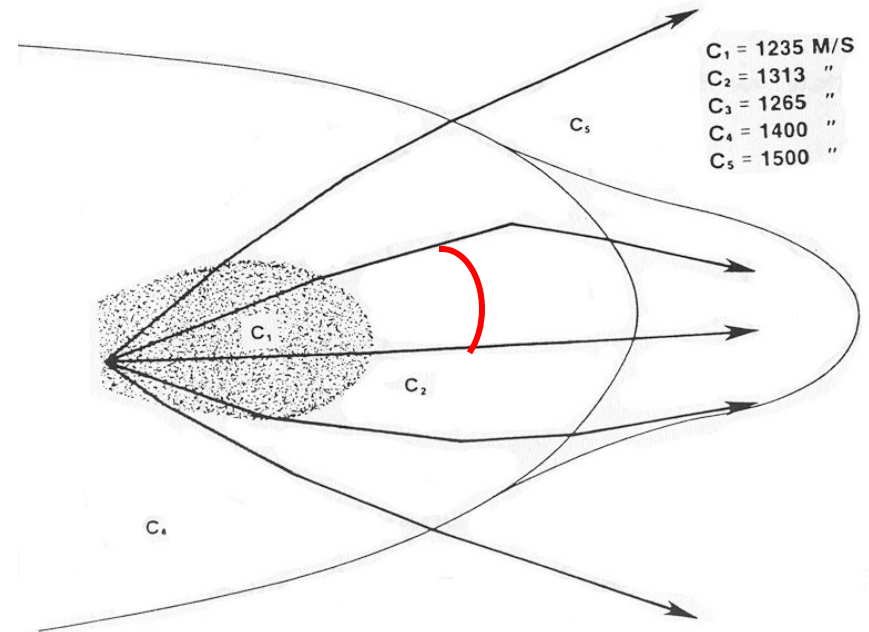
Result: wave fronts are refracted towards the normal

$$\frac{\sin \theta_2}{\sin \theta_1} = \frac{c_2}{c_1}$$

If  $c_2/c_1 = 0.5$ , and  $\theta_1 = 45^\circ$

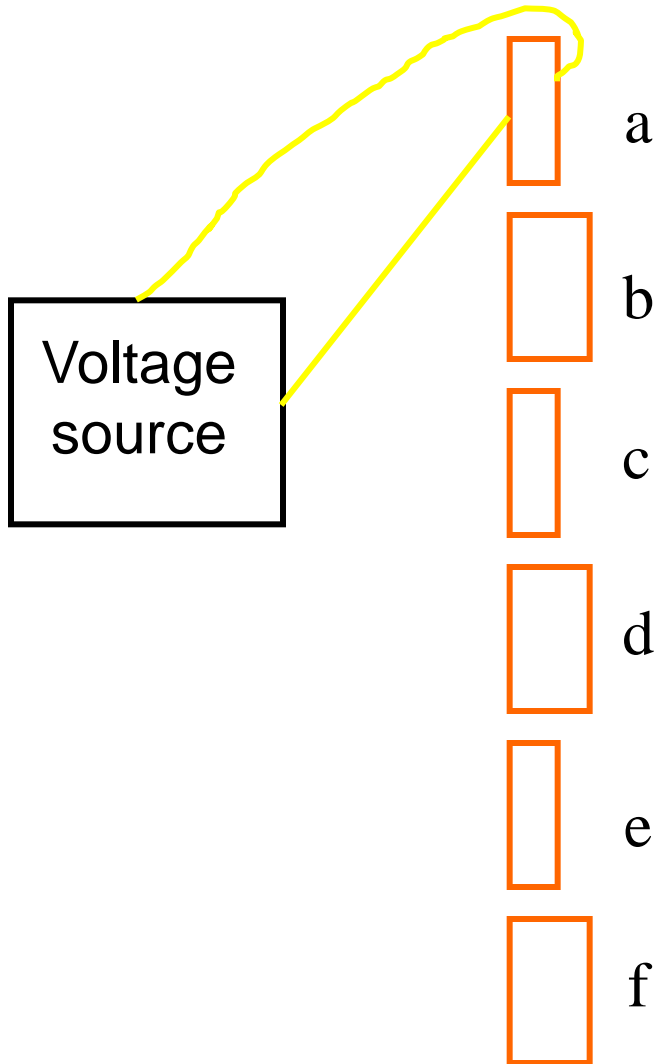
then:  $\sin \theta_2 = \frac{c_2}{c_1} \sin \theta_1 = 0.5 \sin(45^\circ) \Rightarrow 21^\circ$

Bottlenose dolphin (*Tursiops sp.*)

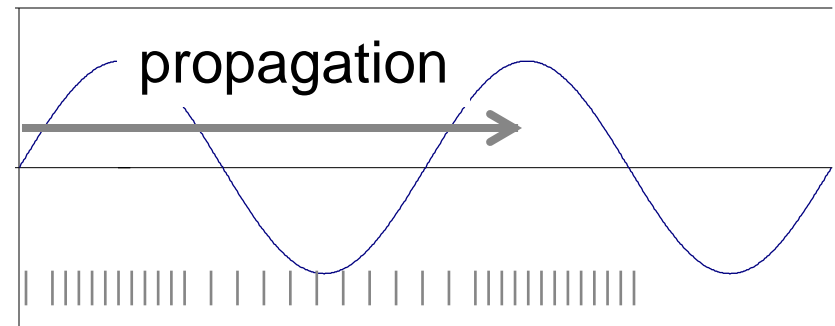
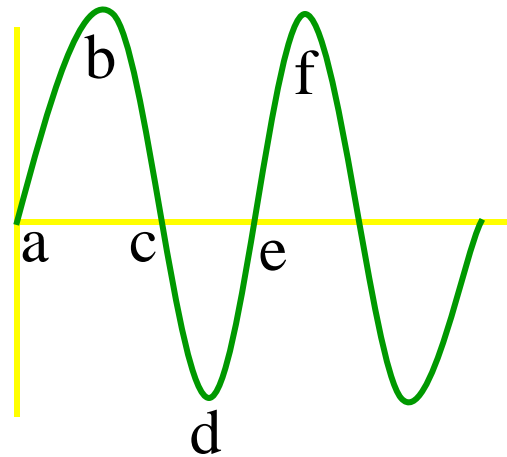


Check the sound speeds and ray paths

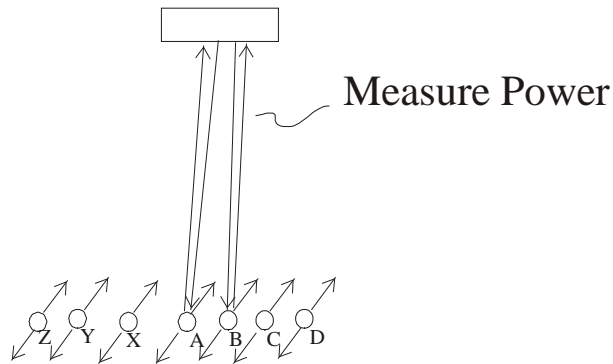
# Producing & Receiving Sound



Oscillatory Signal

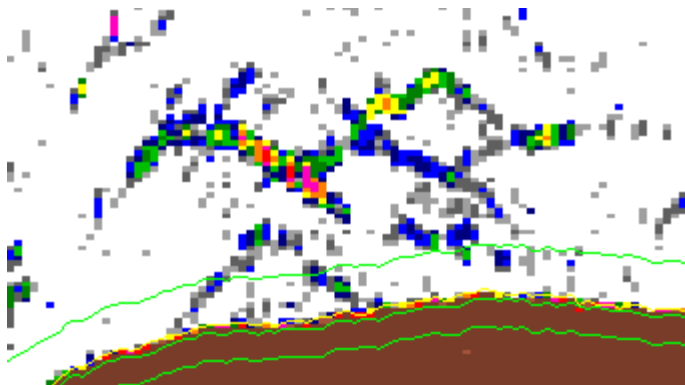


# Transducer Transmit & Receive

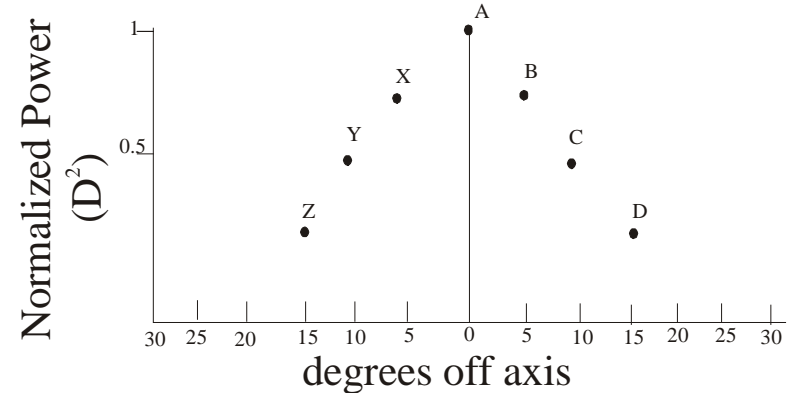


monostatic transducer (or transceiver):  
transmits and receives from same source

bistatic transceiver: transmits from one  
source and receives on a second



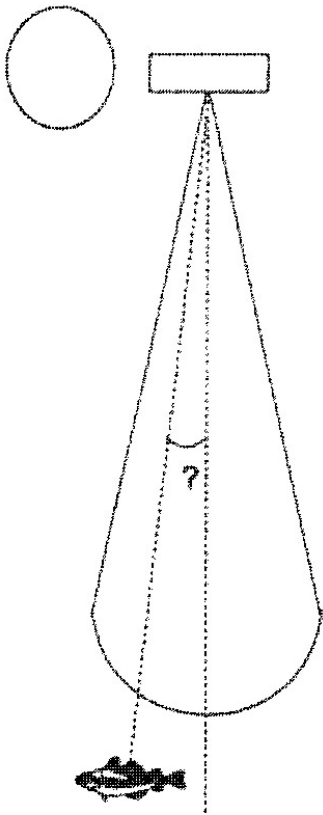
120 kHz, -65 dB threshold



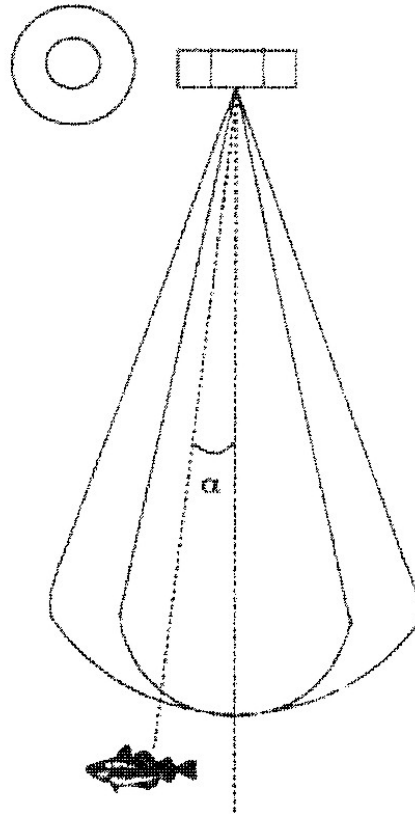
fingernail traces (i.e. boomerangs):  
due to differences in range and  
intensities

# Transducer Types

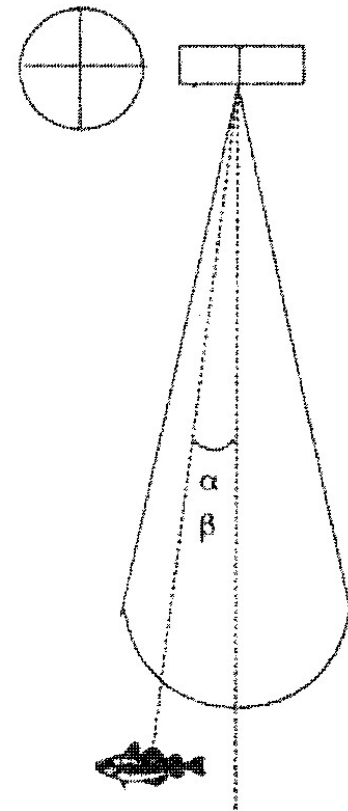
SINGLE BEAM



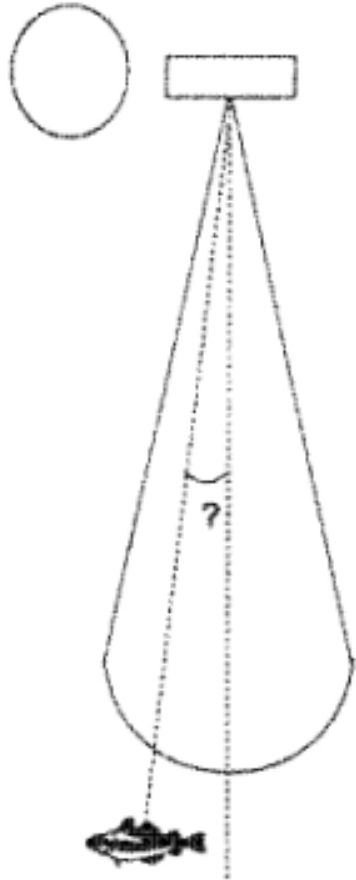
DUAL BEAM



SPLIT BEAM



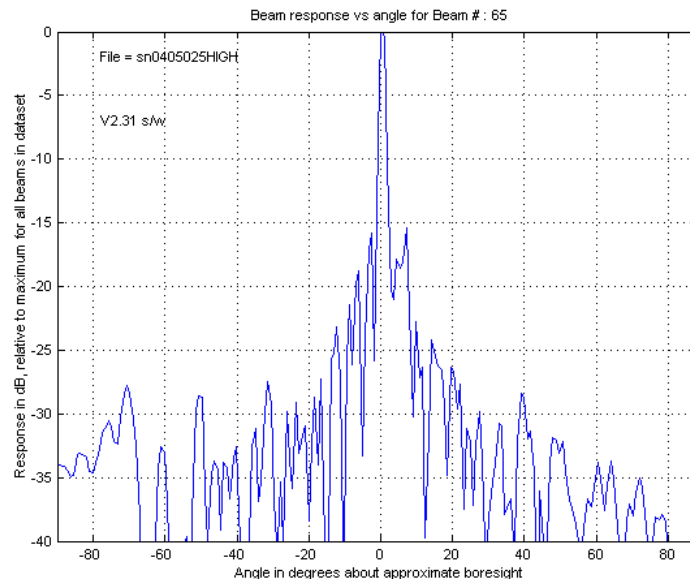
## SINGLE BEAM



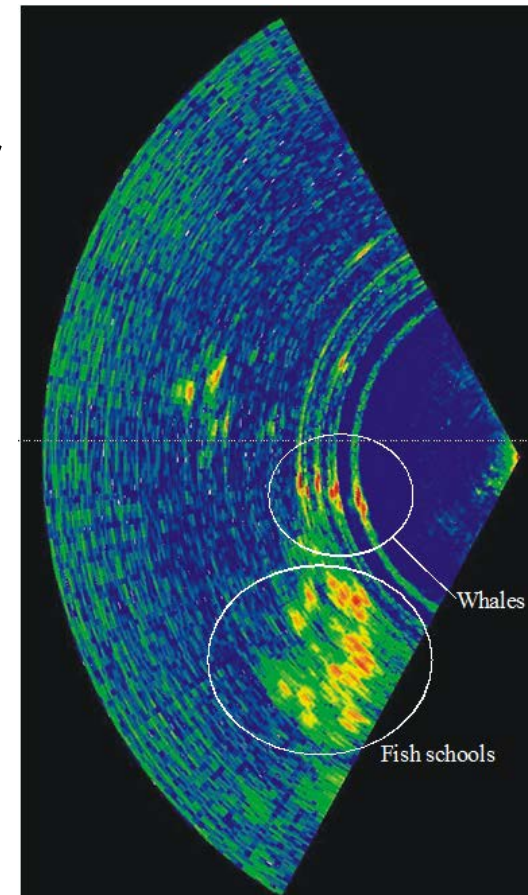
# Single Beam

- no way to locate target within beam
- assume statistical distribution within beam when estimating target strengths (e.g. Craig and Forbes algorithm)

## Single Beam in a Multibeam Sonar

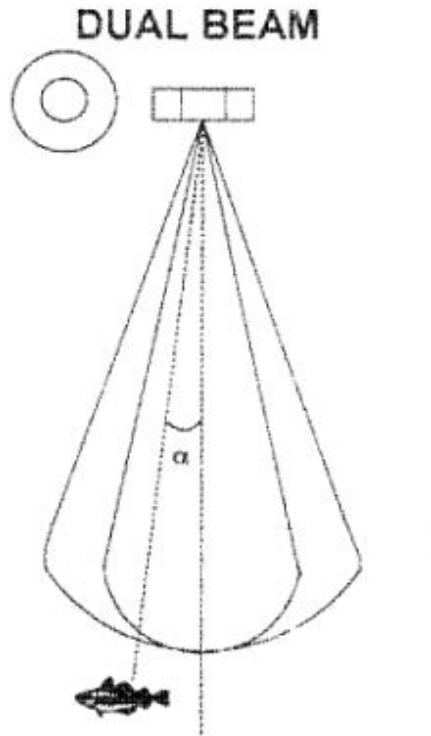


Halo effect from side lobes



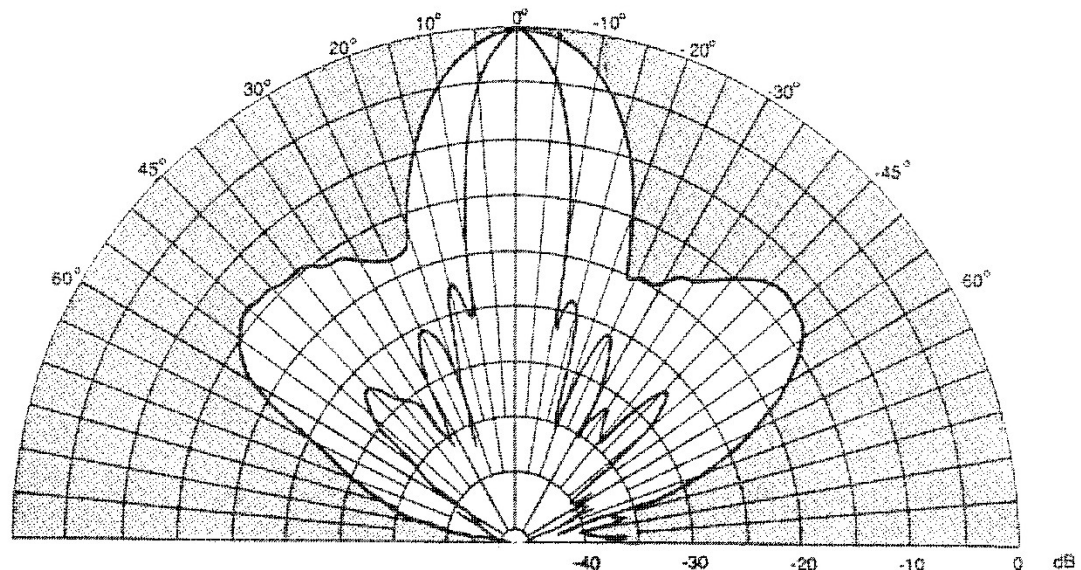


# Dual Beam



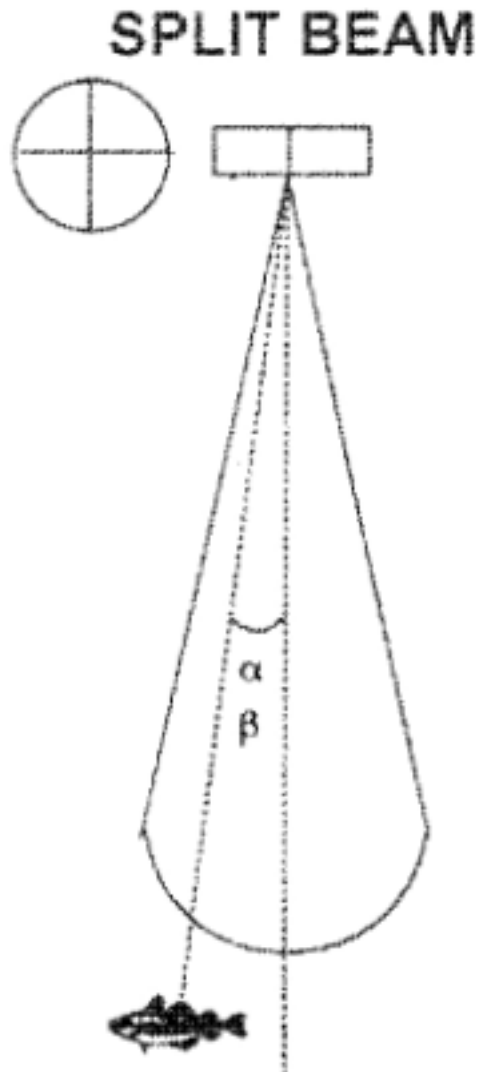
- two concentric beams
- transmit on narrow, receive on narrow and wide
- target angle a function of ratio of voltages received
- provides angle off axis (i.e. a ring)

Beam plot of a dual beam transducer





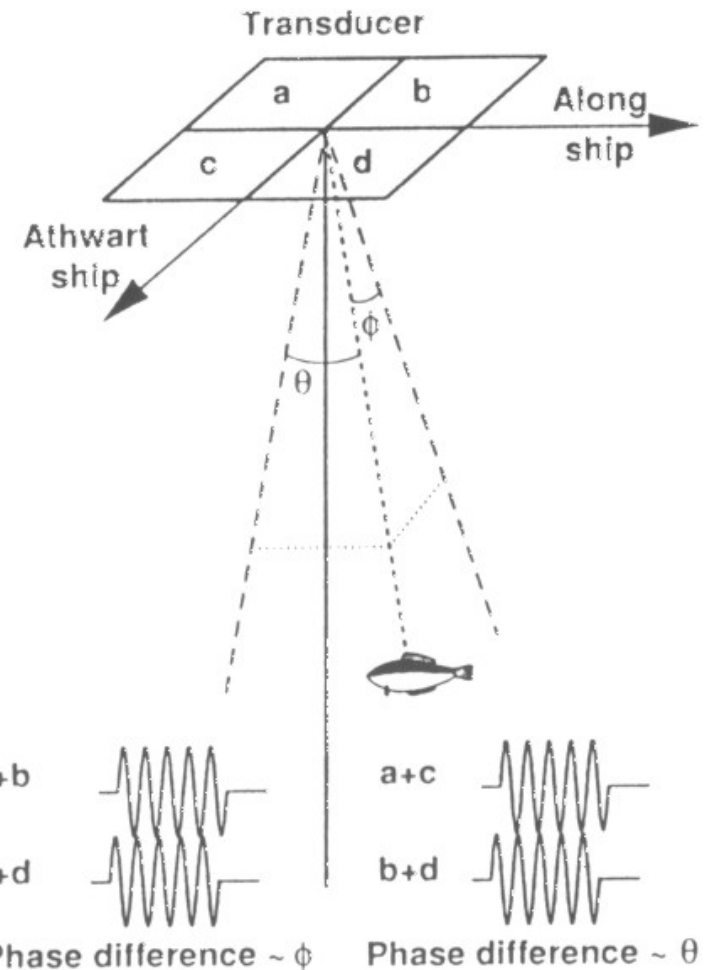
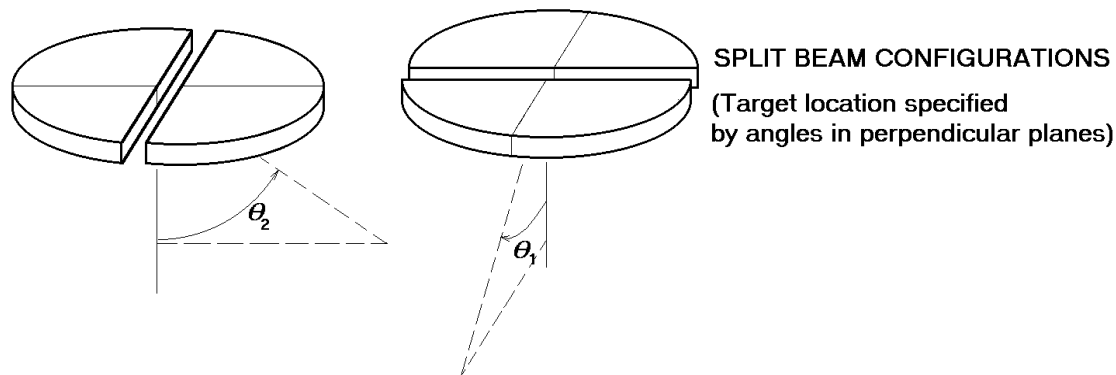
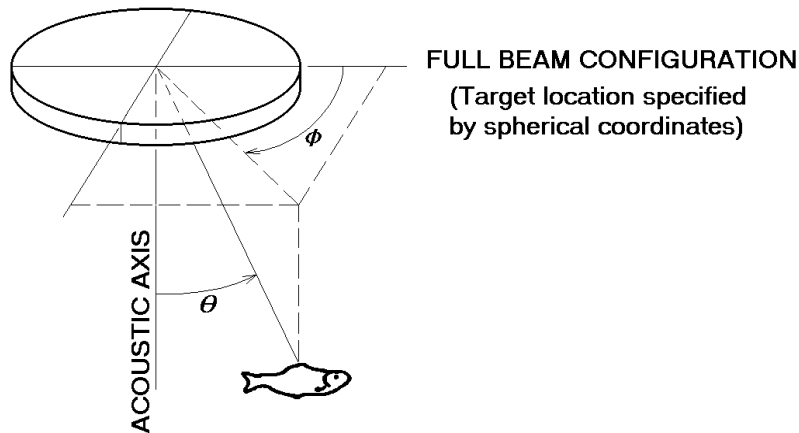
# Split Beam



- transducer receive elements divided into 4 quadrants
- angle along, angle athwart
- use time lag (i.e. phase differences) to derive 2 angles
- provides position in beam at intersection of 2 angles

# Split Beam Phase Differencing

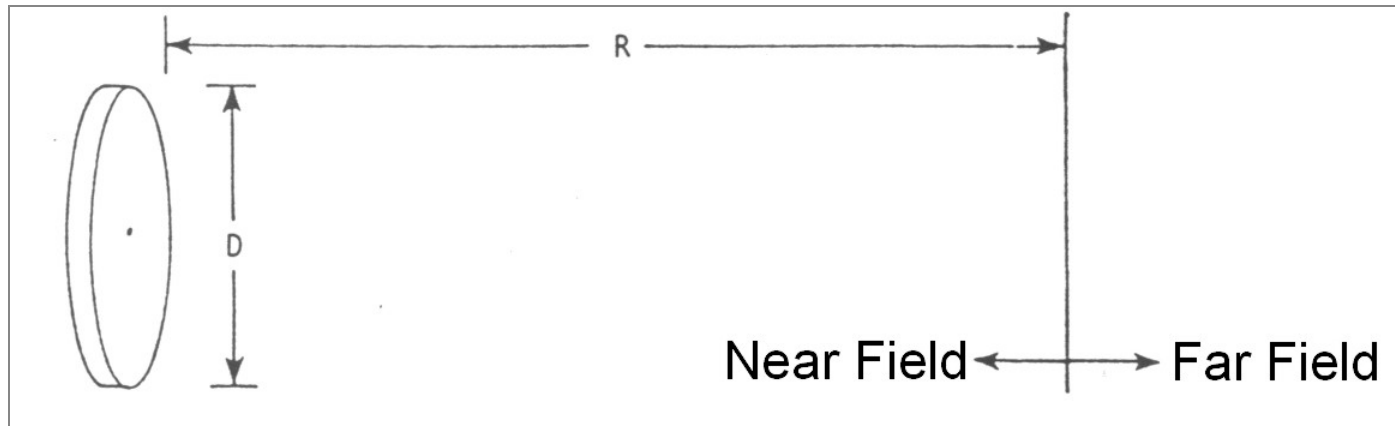
## Split Beam Method



- compare athwart and along echo arrival times
- phase differences used to estimate angles  $\theta$  and  $\phi$

# Near Field & Far Field

Far field: when incident wave front is normal to target



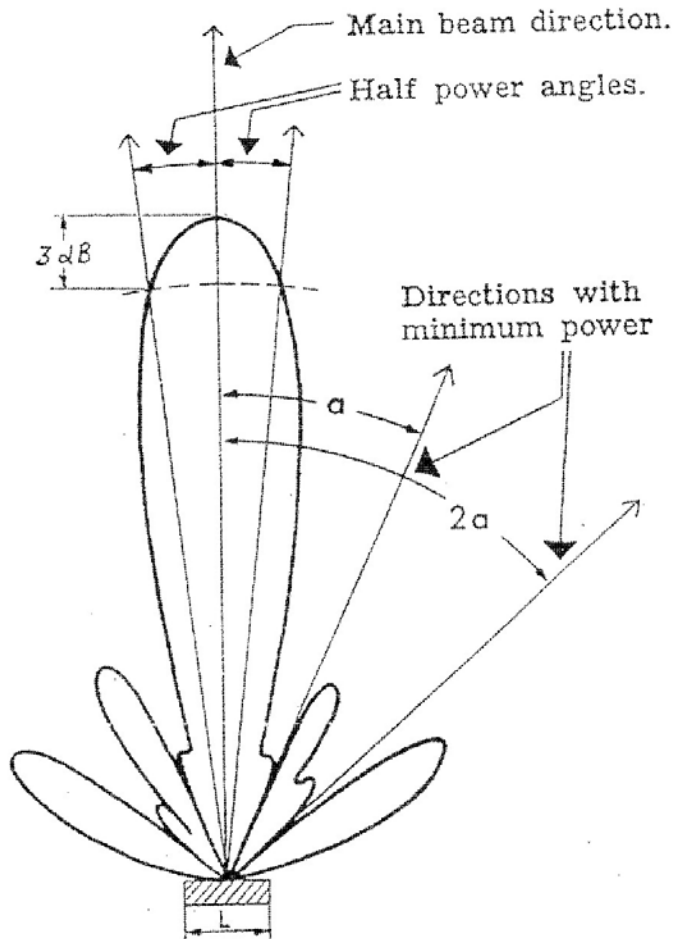
$$r = D^2/\lambda$$

where:

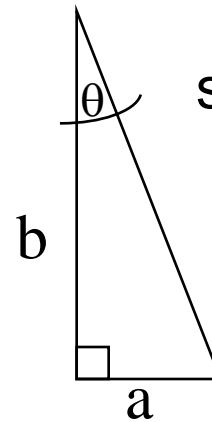
$r$  = far field range,  $D$  = active transducer diameter,  $\lambda$  = wavelength

$$\text{ANSI-ASA S1.20.2013: } R_c = \pi a^2 / \lambda$$

# Swath at Depth



Half power points = -3dB power =  $\theta$



since  $\tan(\theta) = a/b$

(sohcahtoa)

$$swath(depth) = 2depth * \tan\left(\frac{beamwidth}{2}\right)$$

What is swath of a  $7^\circ$  transducer at 100 m? 12.23 m